

Linear Actuators RH 1250

Max. lifting force 4.5 to 12.5 kN, stroke from 80 to 250 mm manual-hydraulic version



Advantages

- High operating safety by speed limiting valve and pressure relief valve
- Optional descent actuation by pushing or turning
- Optional fork or flange mounting
- Precise plunger guide
- Independent of external power supply
- No obligatory tests as per electrical safety regulations
- Compact design
- Single-lever operation
- Maintenance free
- Resistant against disinfectants
- Different lacquerings as an option

Linear actuators RH 1250 manually operated



Issue 6-15 E

Part no.: M8-XX-XX-X-A-X-L-X-X

Technical data

Max. push force: 4,500 – 12,500 N Stroke: 80 – 250 mm

Operations

• Foot pedal or hand lever





Application

Linear actuators RH 1250 are universally used as manually-operated actuators for linear movements.

Principal use

- Height adjustment of hospital and nursing beds as well as mobile nursing chairs
- Height adjustment of patient transporters and therapy couches
- Adjustment of examination and care chairs as well as childbirth beds
- Height adjustment of instrument tables
- Actuator for lifting modules and lifting tables

Description

Linear actuators RH 1250 are manually operated, hermetically sealed, hydro-mechanical actuators for linear adjusting procedures.

The compact design contains the pump piston and the valve technology. Also the oil reservoir and the plunger cylinder are integrated.

The hydraulic transmission in connection with the manual operation allows a good dosage of very high forces.

Important for that are also the mechanics with minimum clearance as well as the sensitive responding valves with exactly defined switching points.

In principle only push forces can be generated.

Mechanical interface

Plunger eye Ø 12 mm Centring pivot Ø 38 mm Optional extra: Fork or flange mounting

Accessories

- Foot pedal
- Hand lever
- Bearing blocks

Material

Body: Aluminium

Operating shaft: Steel, corrosion resistant Plunger: Steel, corrosion resistant

Fixing and installation

The linear actuators RH 1250 have 1 location hole \varnothing 12.1 mm in the plunger and 2 centring pivots \varnothing 38 mm for the connection of user's constructions.

The user's construction must exclude side loads and forced conditions.

The centring pivots \emptyset 38 mm are unlacquered.

There are two different operating directions of the pump lever: clockwise and counterclockwise operation of the pump lever, depending on the user's construction.

Operation

The plunger rod is extended by reversible rotation of approx. 40° by an operating lever at the operating shaft.

The recommended lever length is approx. 300 mm.

To retract the plunger cylinder, the operating shaft has to be turned to the opposite direction by approx. 10°. The operating shaft returns automatically.

Important notes!

The linear actuators RH 1250 are resistant against corrosion, detergents and disinfectants up to +70 $^{\circ}\text{C}.$

The admissible operating temperature is 10° up to 40 °C.

To retract the plunger of the linear actuator a push load of at least 100 N is required.

Technical data and code for part numbers

Functioning

operating lever, that is pinned at the operating shaft.

The integrated flow control valve provides for an uniform descent speed in all load conditions. Due to the possibility to get a drilled operating shaft, the actuator can quickly be installed and put into operation.

All versions of the RH 1250 are operated with an
It has to be considered that the user's construction always acts with push force onto the actuator.

> The actuator has a high safety against overload. In the case of overload it is not possible to continue pumping the actuator, but descent is possible. The operator has to make sure that the actuator is not overloaded.

Technical data

Lifting force	Pump strokes	Required pump torque	v Descent	Release torque Descent	Release angle Descent
[N]	[per 100 mm]	[Nm/full load]	[s/100 mm]	[Nm/full load]	[°]
4500	7±1	160	4.5±1	10	2 – 10
6500	9±1	160	4.5±1	11	2 – 10
9500	13±1	160	4.5±1	15	2 – 10
12500	22±1	120	4.5±1	17	2 – 10

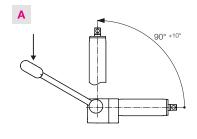
Important notes!

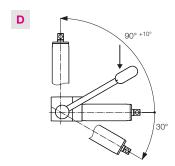
The indicated torques are the maximum torques required for operation.

The return torque of the operating shaft for the pump stroke is max. 6 Nm. The return torque of the operating shaft for the descent is max. 2 Nm. The indicated return torques mus not be exceeded

by the user's constructions of the operating lever. Otherwise, it could be possible that the operating lever will not be moved back to the off-position or an unintentional descent of the actuator could occur.

Admissible mounting positions for operating direction





Available on request:

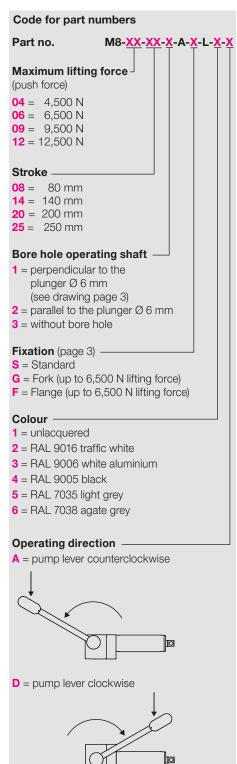
- Stroke lengths up to 600 mm in gradations of 50 mm (up to lifting force 6,500 N)
- Descent actuation by pushing

Variant for emergency adjustment in hospital beds. By pushing the descent bolt, additionally mounted at the actuator, the plunger can be safely pushed in. The descent bolt returns automatically.

· Descent actuation by turning Variant for emergency adjustment in hospital beds. By rotating a descent shaft, additionally mounted at the actuator, the plunger can be safely retracted.

The descent actuation by turning does not return automatically.

- Front-side thread M8 in the plunger
- Versions with low residual magnetism for MRT applications
- Other descent speeds
- Other colours
- · Customised special actuators



The RH 1250 is available in different mounting variants

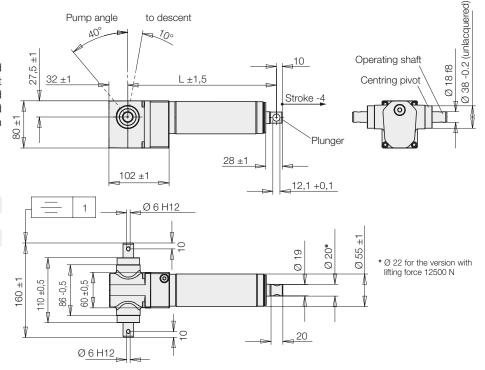
Besides the standard mounting with centring pivot \emptyset 38 mm mounted at the housing, the RH 1250 can be deliverd with fork mounting or flange mounting.



Standard

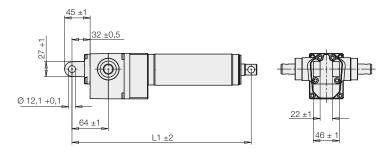
The standard version of the actuator is located by forks or eyes in the user's construction at the centring pivots \varnothing 38 mm and is secured with a bolt \varnothing 12 mm. It has to be considered that the user's construction always acts with push force onto the actuator.

Stroke [mm]	L [mm]	L + stroke [mm]	Weight [kg]
80	192	272	2.2
140	252	392	3
200	312	512	3.5
250	362	612	4



Fork** For easy mounting by means of flange and bolt.

Stroke [mm]	L1 [mm]	L1 + stroke [mm]	Weight [kg]
80	256	336	2.2
140	316	456	3
200	376	576	3.5
250	426	676	4



Flange **

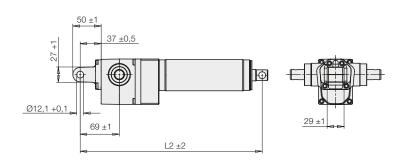
Often selected variant for example in therapy couches. Integration of the actuator in a steel structure by means of fork and bolt.

Stroke [mm]	L2 [mm]	L2 + stroke [mm]	Weight [kg]
80	261	341	2.2
140	321	461	3
200	381	581	3.5
250	431	681	4

** Fork and flange mounting up to a lifting force of 6.500 N available. Forks and flanges have drafts.

Important note!

To avoid an overload of the actuator, external stops are to be provided for the operating elements in order to limit the pump angle to 40°. Also for extensions with far-off levers supports for torque compensation have to be provided.



Subject to modifications

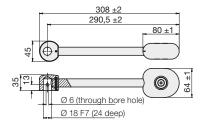
Accessories Important notes

Accessories

Foot pedal

Pre-drilled for the arrangement of 90° to the shaft bore hole

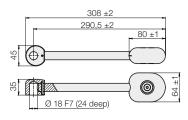
Part no. 0990-180



• Foot pedal

Without bore hole for application-specific arrangement.

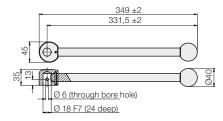
Part no. 0990-181



• Hand lever

Pre-drilled for the arrangement of 90° to the shaft bore hole

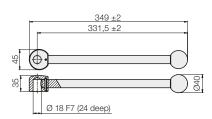
Part no. 0990-182



• Hand lever

Without bore hole for application-specific arrangement.

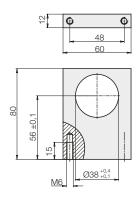
Part no. 0990-183



Bearing block

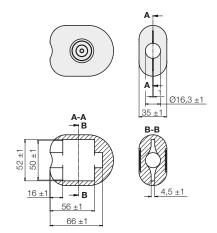
For location of the RH 1250 at the bearing eyes Ø 38 2 off are required

Part-no. 3537-289



• Pedal cover, black

For application-specific lever or as spare part **Part-no. 3549-002**



Important notes

The RH 1250 is not suitable for pull load. If the plunger will be loaded by pulling, air can be pulled into the hydraulic system and this can lead to malfunctions. This can be eliminated by repeated extension and retraction of the actuator.

Subject to modifications